EE CprE 492 – May 21 - 27 MicroCART Senior Design Team Bi-Weekly Report 2

February 8 - February 21 Faculty Advisors: Phillip Jones

Team Members:

Alex Bjerke — Project Manager

Amith Kopparapu Venkata Boja — Embedded Software Lead

Theodore Davis — Embedded Hardware Lead | System integration

Grayson Goss — Technical Lead | CAD Design Lead

Hannah Mohamad — Team Webmaster

Russ Paulsen — Test Station Lead

Alfonso Raymundo — PCB Design Lead

Trent Woodhouse — High-Level Software Lead

Past Week Accomplishments

- UART Synchronous Functionality
 - Can send a receive bytes of data over the rx and tx pins.
 - Found that io_read() polls so you should only read one byte at a time after checking if the fifo isn't empty so it doesn't lock.
- Ground Control Start Commands Trent
 - Ground control cli and gui can both start from a single command
- Measured current draw for the motors. Note: this does not account for mcu use as the controller was idle at the time as well as the other peripherals.

Per % duty cycle	Amps							
20	0.05	Chart Title						
40	0.081	0.18 Chart little						
60	0.113	0.16						
70	0.14	0.14					-	
80	0.154	0.12				/		
		0.1						
Capacity / use per hour	Time in mins	0.08			1			
0.811688312	48.7012987	0.06		1				
		0.04						
		0.02						
2 motors at 40 % duty cycle	0.303	0		20	40	60	80	100
								100
calculated 4 motors at 40 %	1.152							
Capacity / use	Time in mins							
0.434027778	26.04166667							

Pending Issues

Individual Contributions

Team Member	Contribution	2-Week Hours	Total Hours	
Alex	Ground control: worked on supported commands, logging, and packet implementations	8	84	
Alfonso	Worked with Hannah to set up Drone soldering & spent most time unsoldering Wing. worked on putting Drone together on a breadboard.	10.5	89.25	
Amith	Wrote a very debug friendly code to retrieve I2C data. Tested it with arduino as slave and ran into blockers.	27	101	
Grayson	Ran several tests to gauge output of rotational encoder, and began drafting ideas to implement data transmission from encoder to an Arduino product. Also met with Mech E friend to begin CADing up changes to current test station design.	14	93	
Hannah	Worked with Fonzy on building up the drone and Bills of Materials	6	53	
Russ	Looked at last years design more.	7	63	
Theodore Davis	Worked with Amith on understanding i2c. Finished getting UART functionality to work.	7.5	86	

Trent	Made shell command to run both c server and UI,	9.5	59.5
	developed UI for connecting new devices		

Plans for Coming Week

- Theo -
 - Wrap UART functionality into its own file.
 - Start on SPI functionality.
- Alex -
 - Test the rest of the implemented commands
 - Test packet functions
 - Finish logging implementation
- Fonzy -
 - Unsoldering Wing for later use.
 - Finish putting Drone together on a breadboard.
- Hannah
 - Putting up Drone together on the breadboard
- Amith
 - Finish up I2C setup
 - Format the I2C data received from the sensor and send it through wifi from UART.
- Trent
 - Add test station graphs
 - Begin work on logging
- Grayson
 - Studying for exams in biomed classes this week may get in the way of plans but here's what I have:
 - Run more tests with an Arduino controller to see if my data capture ideas are correct. If not, correct them.
 - Meet with Mech E friend again to further work on CAD of test station
 - Meet with Russ to see how he is doing with working on previous design modifications.